Product Recommendation Information Sheet

Opening and Shutting Doors

| Desired P | roduct If you have no | desired product, | eave the applicable fields | s blank. We will cal | you if necessary. | | | | |
|---|---------------------------------|---------------------|----------------------------|------------------------------|---------------------------|-----------|-------------------------|----------------------------------|--|
| Desired Motor(s) | | | | | | | | | |
| \square $oldsymbol{\mathcal{O}}$ STEP | ☐ Stepper Motor | | Servo Motor | ☐ Elect | ric Actuator | | Brushless Moto | or | |
| ☐ AC Motor | Others | | | | | | | | |
| ■Drive Med | hanism Specif | ications | If in doubt, leave | the applicable field | s blank. We will call you | if necess | ary. | | |
| Rotating Body Dime | | | | | | ř. | | <u> </u> | |
| ● Width ········ | | · A = | mm | | | i | | Rotating Body | |
| ● Vertical······· | | · B = | mm | | | | | | |
| ■ Eccentricity \ | /olume······ | · e = | mm | | | į | | | |
| Rotating Bod | y Thickness ····· | · C = | mm | | | | | | |
| Rotating Bod | y Mass or Material······ | · m = | kg o | r material→ | | | | Motor | |
| Position of M | echanism | | | | | | | Wotor | |
| OHorizontal | Plane Rotation | Widt | h A Vertical B | | | | | Center of Gravity | |
| | Thicknes | ss CI | | | <u>C</u> | enter of | Rotation | B | |
| | | | | | | | e | | |
| | | 10/1:444- | | | | | Ĉ. | A | |
| O Vertical Pla | | Width A | Thickness C | | | | | | |
| | Vertical I | BÎ • | | | | | | | |
| | | | | | | | | | |
| Please enter if you | use connecting belt pul | ley or gear. I | Not required for d | irect connec | tion. | | | | |
| Primary Side Pu | lley Diameter and Mass | · D _{P1} = | mm | <i>m</i> _{P1} = | kg | | | | |
| If the ma | ass is unknown, please | enter the wid | th and material. | → [<i>L</i> _{P1} = | m | m | Materials: | | |
| Secondary Side | Pulley Diameter and Mass | · D _{P2} = | mm | <i>m</i> _{P2} = | kg | | | | |
| If the ma | ass is unknown, please | enter the wid | dth and material. | → L _{P2} = | m | m | Materials: | | |
| | | | | | | | | | |
| ■ Operating | Conditions • | in doubt, leave the | e applicable fields blank. | We will call you if r | ecessary. | | | | |
| ■ Travel Amour | nt per Rotation Angle | | 0 | Rotation | Speed N | | | | |
| | ime······ | | S | | | | | | |
| _ | ation and Deceleration Time | | S | | Rotation Angle [*] | | | | |
| ■Stop Time ···· | | · t2 = | s | | | | | | |
| Desired Travel R | Rotation Speed (If any) ······· | · N = | to | r/min | - Acc | | Deceleration Time to | | |
| Desired Stop | ping Accuracy (If any) | . ± | • | 7 | Posi | tioning | Time to [S] | Stopping Time t ₂ [S] | |
| • | y Voltage ······ | | V, | <u> </u> |] | | | | |
| | Iding Force After Power is Tu | | ○ Yes | ○ No | , | | | | |

| Others | | | | | | | |
|--|---------|--|--|--|--|--|--|
| Application, Equipment Name····· | | | | | | | |
| Estimated Number of Units to be Used ····· | unit(s) | | | | | | |
| Estimated Purchase Date | | | | | | | |
| Supply Source (Sales office) ····· | | | | | | | |
| Other (Requests, Contact information, Items not written above, etc.) | | | | | | | |
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